WEST Search History

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DATE: Sunday, March 22, 2009

Hide?	Set Name	Query	Hit Count
		DB=USPT; PLUR=YES; OP=ADJ	
☐	L94	foot and L93	17
☐	L93	float$4 and L92	18
☐	L92	"0" and L91	71
☐	L91	robot$6 and L90	92
☐	L90	L89 and zmp	92
☐	L89	(700/245 I700/246 I700/251 I700/253 I700/260 I700/261 318/568.1 I 318/568.12 I318/568.16 I318/568.17 I318/568.2 901/1 I901/9 I901/46 180.1).ccls.	2246
☐	L88	(("6962220")!.PN.) .p67-p150.	1
		DB=PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ	
☐	L87	robot$6 and (walk$3 or biped or humanoid or two legged) and (inlina$6 or betn or tilt or deviat$5 or obliqu$5 or indirect$4 or change direction or slope or slant)	6284
☐	L86	('6711469' I'6697709' I'6567724' I'6505098' I'6493606' I'6480761' I'6330494' I'6289265' I'6243623')!.ABPN1,NRPN,PN,TBAN,WKU.	16
☐	L85	marc.xa. and legged and inclination	35
☐	L84	marc.xa. and legged and inclinaiton	0
☐	L83	('5404086')!.ABPN1,NRPN,PN,TBAN,WKU.	2
☐	L82	(editing or updating) and (motion or traject$4 or movement) and zmp and robot$6	27
☐	L81	(editing or updating) same (motion or traject$4 or movement) and zmp and robot$6	12
☐	L80	(editing or updating) same (motion or traject$4 or movement) and L79	10
☐	L79	robot and zmp and yaw	169
☐	L78	marc.xa. and zmp	47
☐	L77	10/181500	3

☐	L76	('6697709' l'6289265' l'6243623')!.ABPN1,NRPN,PN,TBAN,WKU.	6
☐	L75	marc.xa. and robot and zmp	47
☐	L74	(motions or movement or displacement) and L73	122
☐	L73	computer and L72	135
☐	L72	record$3 and L71	135
☐	L71	(request or command) and L70	166
☐	L70	L66 and L69	174
☐	L69	execut$5 and L68	312322
☐	L68	run or L66	1389091
☐	L67	(6458772 or 6284156 or 6348461 or 6262044 or 6410586 or 6342245 or 6277877 or 6399557 or 3857856 or 5835892 or 6376445 or 6440911 or 6163111 or 5610305 or 5230889 or 4391489 or 4483594 or 6410749 or 4876009 or 6358945 or 6281227 or 6391397 or 6432994 or 4920120 or 5874378 or 6374641 or 5384779 or 5523998 or 5537098 or 4260406 or 4293439 or 4386503 or 5179438 or 5208607 or 6275216 or 5534261 or 5640119 or 5831440 or 6049212 or 6271251 or 4949326 or 5015815 or 5194938 or 4870247 or 6258470 or 6316465 or 6388989 or 4505827 or 5210848 or 5230070).pn.	98
☐	L66	(similar or "same") function and L65	201
☐	L65	robot and control software and (chang$3 or replac$5)	2160
☐	L64	('20050125099')!.ABPN1,NRPN,PN,TBAN,WKU.	2
☐	L63	(10/126774 l 10/970977 l 10/935607 l 10/919172 l 10/775845 l 10/732446 l 10/726597 l 10/683496 l 10/637890)	18
☐	L62	(motion or displacement or trajector$3) and L61	116
☐	L61	(humanoid or two legged robot and human like robot) and zmp and comput$5	119
☐	L60	zmp and "approximately 0"	20
		DB=PGPB,USPT; PLUR=YES; OP=ADJ	
☐	L59	(("20060106495")!.PN.).PGPB. l (("7119510")!.PN.).USPT.	2
		DB=PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ	
☐	L58	grasping and L57	6
☐	L57	horizontal and vertical and L56	20
☐	L56	signal and detection and L55	20
☐	L55	distance and L54	23

☐	L54	center and L53	28
☐	L53	motion and L52	30
☐	L52	gravity and L51	31
☐	L51	floor reaction and L50	37
☐	L50	foot and robot and ground contact and sensor and sole and joint and reaction and force and walk$3	55

DB=PGPB; PLUR=YES; OP=ADJ

☐	L49	L48	1

DB=PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ

☐	L48	10/553278	1
☐	L47	L46 and robot	13
☐	L46	metatarsophalangeal	540
☐	L45	ground and contact and L43	26
☐	L44	groung and contact and L43	0
☐	L43	sensor and L42	34
☐	L42	axis and L41	34
☐	L41	soles and L40	34
☐	L40	foot and L39	39
☐	L39	L38 and coordinate	39
☐	L38	position and orientation and L37	44
☐	L37	(L9 or L10) and L36	85
☐	L36	landed and landing and foot and robot$6	153
☐	L35	landed and landing and foot and footstep and robot$6	6
☐	L34	landed and landing and foot and footstep and (L9 or L10)	3
☐	L33	landded and landing and foot and footstep and (L9 or L10)	0
☐	L32	landded and landing and foot and footstep and L23	0
☐	L31	landded and landing and foot and L30	0
☐	L30	posture and L29	52
☐	L29	gravity and coordinate and L28	53
☐	L28	estimat$3 and position and L27	62
☐	L27	dynamics same model and L24	74

☐	L26	dyanamics and L24	0
☐	L25	dyanamics same model and L24	0
☐	L24	L22 and L23	184
☐	L23	movement or trajectory and L22	2694961
☐	L22	floor and zmp and L9	193
☐	L21	floor and zmp and L20	0
☐	L20	(5024920 | 5173382 | 5490103 | 5557564 | 5901829 | 6201488 | 6521838 | 6518503 | 6695663 | 6592418 | 5733819 | 6027554 | 6663326 | 6694847 | 6685863 | 4252414 | 4588518 | 4561746 | 4719331 | 5118090 | 5434926 | 5419740 | 5558196 | 5527940 | 5716481).pn.	47
☐	L19	motion pattern and L17	2
☐	L18	motion pattern and stor$3 and L17	0
☐	L17	freedom and L16	5
☐	L16	L14 and L15	6
☐	L15	L14 and gait or gate	1273890
☐	L14	('6580969' l'6493606' l'6463356' l'6289265' l'6243623' l'5872893' l'5841258' l'5838130' l'5594644' l'EP 1136193A' l'EP 1103451A')!.ABPN1, NRPN,PN,TBAN,WKU.	18
☐	L13	('20030019671' l'20020138359' l'6591923' l'6458011')!.ABPN1,NRPN,PN, TBAN,WKU.	7
☐	L12	(legged robot or pet robot or humanoid near10 robot) motion and pattern	13
☐	L11	(legged robot or pet robot or humanoid near10 robot) motion and pattern and L10	0
☐	L10	(6252544 | 6493606 | 6243623 | 6289265 | 5673367 | 5355064 | 5455497 | 5325031 | 5357433 | 5594644 | 6580969 | 6718231 | 5504841 | 5842533 | 4621333 | 4633059 | 4987527 | 5937398 | 6064168 | 6429812 | 6584377 | 5259064 | 5349646 | 5946041 | 4540211 | 4762261 | 5273296 | 5616917 | 5627440 | 5794621 | 6059092 | 6059092 | 6068201 | 6456728 | 6505098 | 6711469 | 5402050 | 5525883 | 5841258 | 6463356 | 4614504 | 5040626 | 5343397 | 5369346 | 5378969 | 5644204 | 5672924 | 5838130 | 5872893 | 6229552).pn.	97
☐	L9	(700/245 l700/246 l700/251 l700/253 l700/260 l700/261 or 318/568.1 l 318/568.12 l318/568.16 l318/568.17 l318/568.2 or 901/1 l901/9 l901/46 or 180/8.1 l180/8.6 l180/65.1 or 701/23 or 320/116 l320/120 or 446/376 l 446/384).ccls.	10678
☐	L8	6580969.pn.	2

☐	L7	11/456454	2
☐	L6	10/511608	1
☐	L5	coordinate and L4	7
☐	L4	"foot-sole" and L2	22
☐	L3	"based on" and L2	48
☐	L2	foot same position same sole	4883
☐	L1	takenaka.in. and floor reaction force and position	102

END OF SEARCH HISTORY